

Guaranteed Characterization of the Area Explored by an Autonomous Robot

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- ① Introduction
- ② Problem Statement
- ③ Problem Approach
- ④ Calculating the Winding Number
- ⑤ Daurade Mission
- ⑥ Conclusions and Future Work



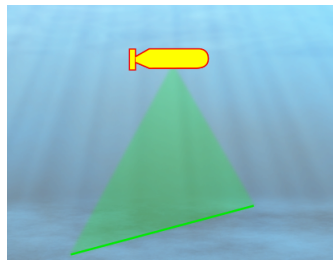
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Introduction

Explored Area

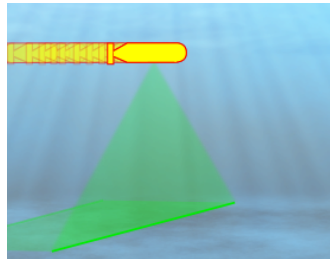
The explored area is the union of the visible areas over the whole trajectory.



Introduction

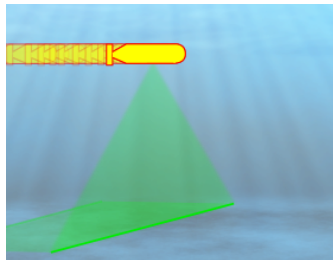
Explored Area

The explored area is the union of the visible areas over the whole trajectory.



Problem

- Calculate the explored area.
- Calculate the number of times each point in the environment has been explored.



Applications

- **Assess area-covering missions**
 - Determine if a mission is complete
 - Plan other missions to fill possible gaps
- **Guarantee** that if a target is not detected, the target does not exist.



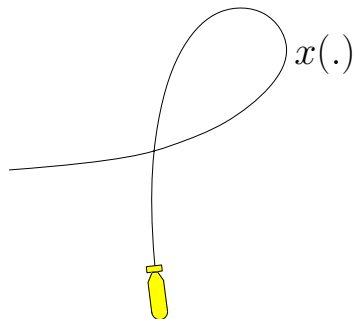
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Problem Statement

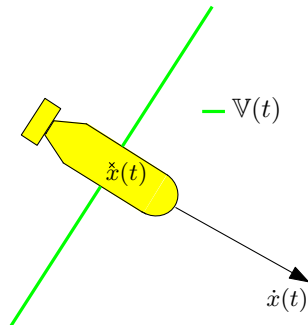
Hypothesis

- $x(.) : \mathbb{R} \rightarrow \mathbb{R}^2$
- $T = [0, T_{max}]$
- $x(.)$ is continuous in T .
- $x(.)$ and $\dot{x}(.)$ are known.



Problem Statement

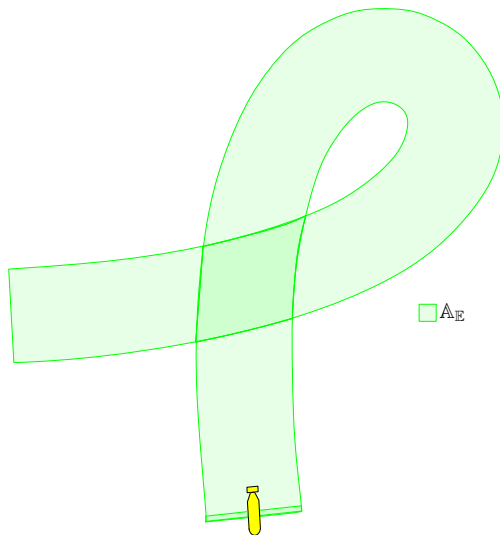
- $\mathbb{V}(x(t), \dot{x}(t))$ is the visible area at time t .



Problem Statement

A_E is the explored area

$$A_E = \bigcup_{t \in T} V(t)$$



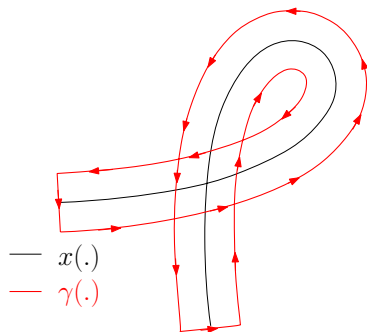
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Sonar Contour

From the robot's trajectory $x(\cdot)$ and the knowledge of the range of visibility of each observation sensor, the sonar contour $\gamma(\cdot)$ can be defined as illustrated.

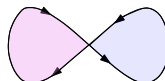
- $\gamma(\cdot) : \mathbb{R} \rightarrow \mathbb{R}^2$
- $T_\gamma = [0, 1]$
- $\gamma(\cdot)$ is continuous in T_γ .
- $\gamma(0) = \gamma(1)$.



Winding Number

Winding Number

The winding number $\eta(\gamma(.), p)$ of a closed curve $\gamma(.)$ in the plane around a given point p is an integer representing the total number of times that curve travels counterclockwise around the point. [1]



Winding Number :

□ -1

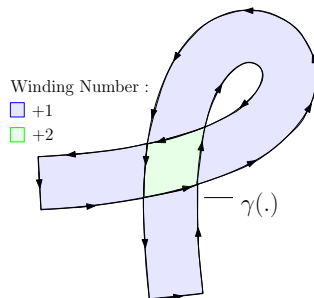
□ +1

□ +2



Problem Approach

$$\mathbb{A}_E = \{z \in \mathbb{R}^2 | \eta(\gamma(.), z) \neq 0\}$$



Problem Approach

Entries

- $\gamma(\cdot)$, the sonar's contour.
- $\dot{\gamma}(\cdot)$, the contour's derivative.



Problem Approach

Entries

- $\gamma(\cdot)$, the sonar's contour.
- $\dot{\gamma}(\cdot)$, the contour's derivative.

Desired Output

- Guaranteed approximation of the explored area $\mathbb{A}_{\mathbb{E}}$.
- Number of times each point in $\mathbb{A}_{\mathbb{E}}$ was seen during the mission.

Proposed solution

$$\eta(\gamma(\cdot), \cdot)$$

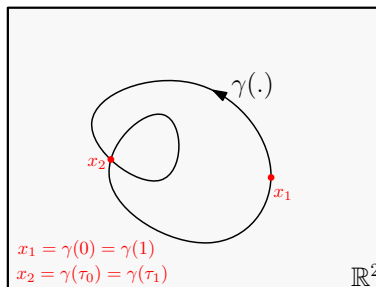


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Self Intersections

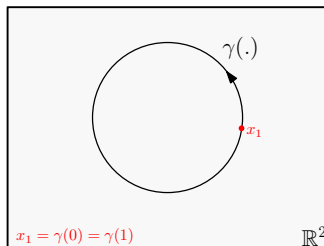
- Let $\gamma(\cdot)$ be a continuous cycle, $\gamma(\cdot) : [0, 1] \rightarrow \mathbb{R}^2$,
- A self-intersection of $\gamma(\cdot)$ determined by parameters (τ_0, τ_1) , is a point x such that $x = \gamma(\tau_0) = \gamma(\tau_1)$, with $0 \leq \tau_0 < \tau_1 \leq 1$.



Simple Cycle

Simple Cycle (Jordan Curve)

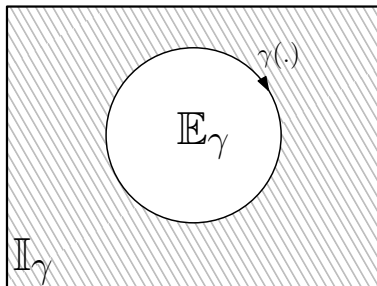
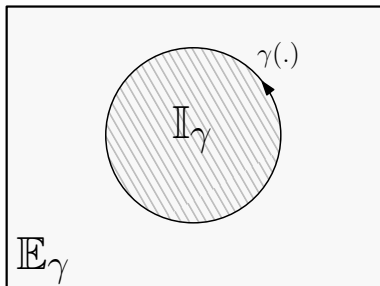
- $\gamma(\cdot)$ is a simple cycle if it has only one self-intersection determined by the unique pair $(0, 1)$.
- $\gamma(\cdot)$ is homeomorphic to S^1 .



Simple Cycle

Jordan Curve Theorem

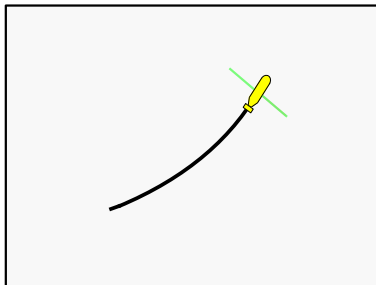
If $\gamma(\cdot)$ is a simple cycle, then it divides the plane into two regions, \mathbb{I}_γ and \mathbb{E}_γ .



Simple Cycle

Jordan Curve Theorem

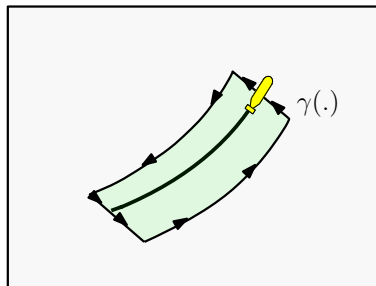
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Simple Cycle

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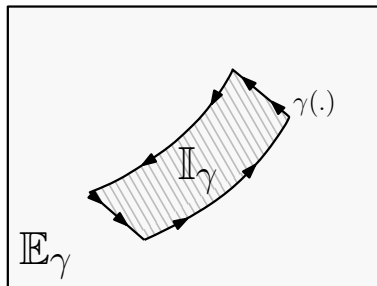
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Simple Cycle

Jordan Curve Theorem

If $\gamma(\cdot)$ is a simple cycle, then it divides the plane into two regions, \mathbb{I}_γ and \mathbb{E}_γ .



The winding number of simple cycles

If $\gamma(\cdot)$ is a simple cycle and $p \in \mathbb{R}^2 \setminus \gamma(\cdot)$,

$$\eta(\gamma(\cdot), p) = \begin{cases} \chi_{\mathbb{I}_\gamma}(p) - 1 & , \text{ if } \gamma(\cdot) \text{ is clockwise oriented} \\ \chi_{\mathbb{I}_\gamma}(p) & \text{otherwise} \end{cases}$$

Where, $\chi_{\mathbb{I}_\gamma}(\cdot)$ is the characteristic function of γ 's interior set \mathbb{I}_γ .

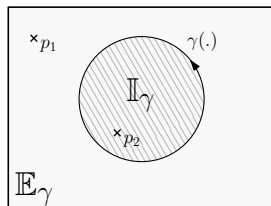


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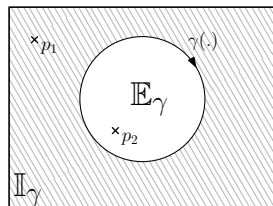
$$\eta(\gamma(\cdot), p) = \begin{cases} \chi_{\mathbb{I}_\gamma}(p) - 1 & , \text{ if } \gamma(\cdot) \text{ is clockwise oriented} \\ \chi_{\mathbb{I}_\gamma}(p) & \text{otherwise} \end{cases}$$

Where, $\chi_{\mathbb{I}_\gamma}(\cdot)$ is the characteristic function of γ 's interior set \mathbb{I}_γ .



$$\eta(\gamma(\cdot), p_1) = 0$$

$$\eta(\gamma(\cdot), p_2) = 1$$



$$\eta(\gamma(\cdot), p_1) = 1 - 1 = 0$$

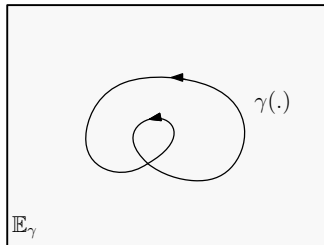
$$\eta(\gamma(\cdot), p_2) = 0 - 1 = -1$$

The winding number of non-simple cycles

Hypothesis

$\gamma(\cdot)$ is a continuous non-simple cycle:

- $\gamma(\cdot) : [0, 1] \rightarrow \mathbb{R}^2$,
- $\gamma(0) = \gamma(1)$,
- $\exists(\tau_0, \tau_1), 0 < \tau_0 < \tau_1 < 1 | \gamma(\tau_0) = \gamma(\tau_1)$.

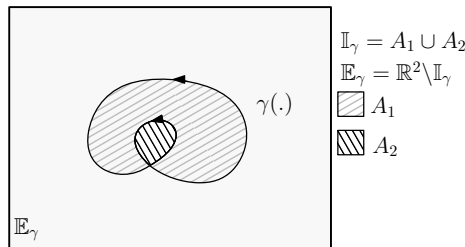


The winding number of non-simple cycles

Hypothesis

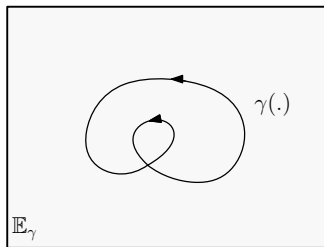
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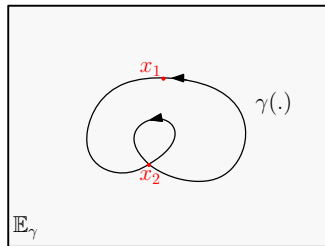
The winding number of non-simple cycles

Cell Decomposition :



The winding number of non-simple cycles

Cell Decomposition :



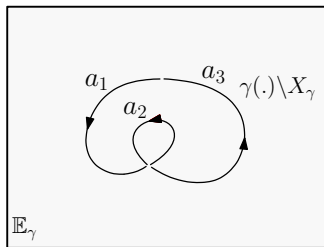
- Self-intersections:**

$$X_\gamma = \{x \in \mathbb{R}^2 \mid \exists(\tau_0, \tau_1), 0 \leq \tau_0 < \tau_1 \leq 1, x = \gamma(\tau_0) = \gamma(\tau_1)\},$$



The winding number of non-simple cycles

Cell Decomposition :



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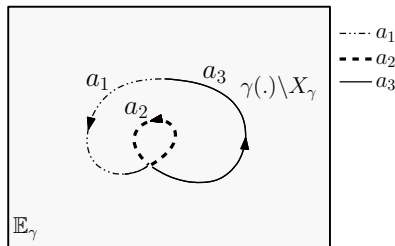
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- Edges :** Connected components of $\gamma(.) \setminus X_\gamma$,



The winding number of non-simple cycles

Cell Decomposition :



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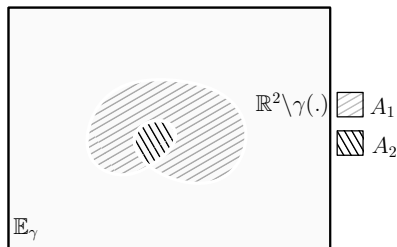
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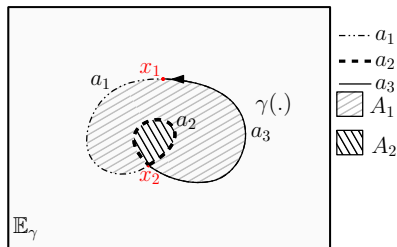
- Edges :** Connected components of $\gamma(.) \setminus X_\gamma$,

- Cells :** Connected components of $\mathbb{R}^2 \setminus \gamma(.)$.



The winding number of non-simple cycles

Cell Decomposition :



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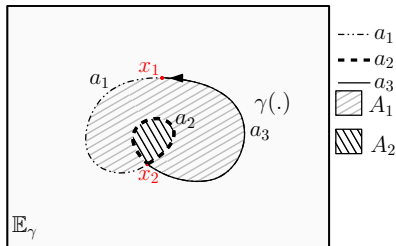
- Edges :** Connected components of $\gamma(.) \setminus X_\gamma$,

- Cells :** Connected components of $\mathbb{R}^2 \setminus \gamma(.)$.



The winding number of non-simple cycles

- A cycle can be algebraically described as a sum of all its edges, this sum results in zero.
- A cycle is simple if no other cycle can be written as a boolean combination of its edges.

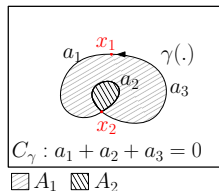


$$C_\gamma : a_1 + a_2 + a_3 = 0$$

$$C_{x_2} : a_2 = 0$$



The winding number of non-simple cycles



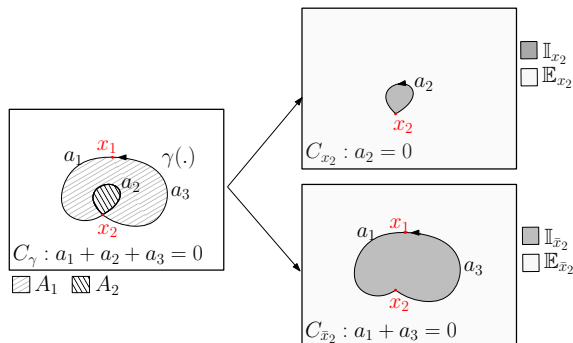
$$C_\gamma : a_1 + a_2 + a_3 = 0$$

$$C_{x_2} : a_2 = 0, \mathbb{I}_{x_2} = A_2$$

$$C_{\bar{x}_2} : a_1 + a_3 = 0, \mathbb{I}_{\bar{x}_2} = A_1 + A_2$$



The winding number of non-simple cycles



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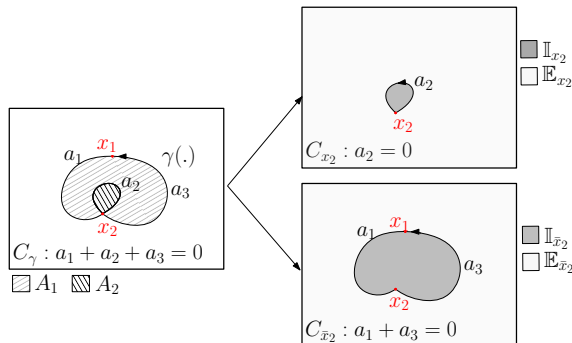
$$C_{\bar{x}_2} : a_1 + a_3 = 0, \mathbb{I}_{\bar{x}_2} = A_1 + A_2$$

$$C_\gamma = C_{x_2} + C_{\bar{x}_2} = 0$$

$$\mathbb{I}_\gamma = A_1 + 2A_2$$



The winding number of non-simple cycles



$$C_\gamma = C_{x_2} + C_{\bar{x}_2} = 0, \quad \mathbb{I}_\gamma = A_1 + 2A_2$$

For $p \in \mathbb{R}^2 \setminus \gamma(\cdot)$,

$$\eta(\gamma(\cdot), p) = \chi_{\mathbb{I}_{x_2}}(p) + \chi_{\mathbb{I}_{\bar{x}_2}}(p)$$



The winding number of non-simple cycles

Let $\gamma(\cdot)$ be a continuous cycle and $p \in \mathbb{R}^2 \setminus \gamma(\cdot)$,

$$\eta(\gamma(\cdot), p) = -Z_\gamma + \sum_{u \in U_\gamma} \chi_u(p)$$

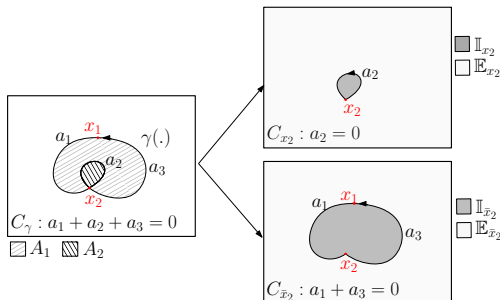
Where,

- U_γ is the generating set of simple cycles such that $\sum_{u \in U_\gamma} u = C_\gamma$,
- Z_γ is the number of clockwise oriented cycles in U_γ ,
- $\chi_{\mathbb{I}_u}(\cdot)$ is the characteristic function of u 's interior set \mathbb{I}_u .



The winding number of non-simple cycles

Example:



$$U_\gamma = \{C_{x_2}(\cdot), C_{\bar{x}_2}\} \text{ and } Z_\gamma = 0$$

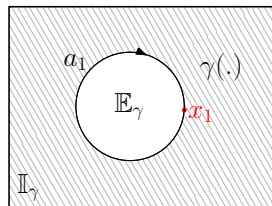
For $p \in \mathbb{R}^2 \setminus \gamma(\cdot)$,

$$\eta(\gamma(\cdot), p) = -Z_\gamma + \sum_{u \in U_\gamma} \chi_u(p) = \chi_{\mathbb{I}_{x_2}}(p) + \chi_{\mathbb{I}_{\bar{x}_2}}(p)$$



The winding number of non-simple cycles

Example:



$$C_\gamma : a_1 = 0$$

$$U_\gamma = \{C_\gamma\} \text{ and } Z_\gamma = 1$$

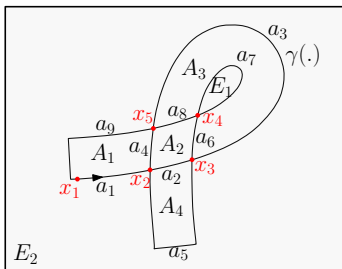
$$\text{For } p \in \mathbb{R}^2 \setminus \gamma(\cdot),$$

$$\eta(\gamma(\cdot), p) = -Z_\gamma + \sum_{u \in U_\gamma} \chi_u(p) = \chi_{I_\gamma} - 1$$



The winding number of non-simple cycles

Example:



Cell Decomposition :

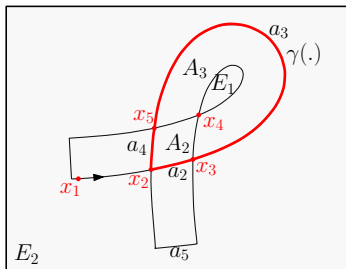
- $X_\gamma = \{x_1, x_2, x_3, x_4, x_5\}$
- $a_\gamma = \{a_1, a_2, a_3, a_4, \dots, a_9\}$
- $A_\gamma = \{A_1, A_2, A_3, A_4, E_1, E_2\}$

$$C_\gamma : a_1 + a_2 + a_3 + a_4 + a_5 + a_6 + a_7 + a_8 + a_9 = 0$$



The winding number of non-simple cycles

Example:



$$C_\gamma : a_1 + a_2 + a_3 + a_4 + a_5 + a_6 + a_7 + a_8 + a_9 = 0$$

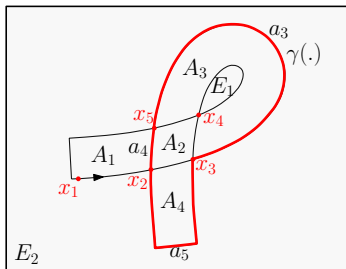
$$C_{x_2} : a_2 + a_3 + a_4 = 0$$

$$\mathbb{I}_{x_2} = A_2 + A_3 + E_1$$



The winding number of non-simple cycles

Example:



$$C_{\gamma} : a_1 + a_2 + a_3 + a_4 + a_5 + a_6 + a_7 + a_8 + a_9 = 0$$

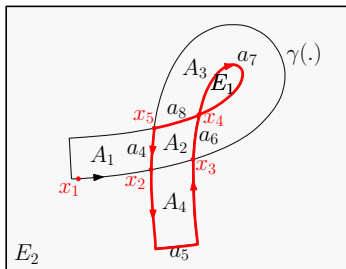
$$C_{x_3} : a_3 + a_4 + a_5 = 0$$

$$\mathbb{I}_{x_3} = A_2 + A_4 + A_3 + E_1$$



The winding number of non-simple cycles

Example:



$$C_\gamma : a_1 + a_2 + a_3 + a_4 + a_5 + a_6 + a_7 + a_8 + a_9 = 0$$

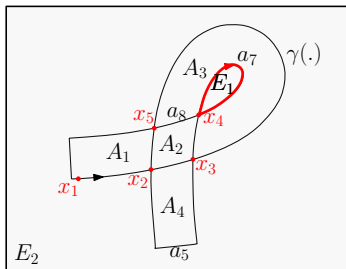
$$C_{x_5} : a_4 + a_5 + a_6 + a_7 + a_8 = 0$$

$$\mathbb{I}_{x_5} = A_2 + A_4 - E_1$$



The winding number of non-simple cycles

Example:



$$C_\gamma : a_1 + a_2 + a_3 + a_4 + a_5 + a_6 + a_7 + a_8 + a_9 = 0$$

$$C_{x_5} : a_4 + a_5 + a_6 + a_7 + a_8 = 0$$

$$C_{x_4} : a_7 = 0$$

$$\mathbb{I}_{x_4} = -E_1$$



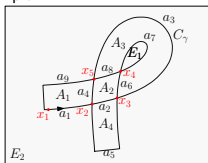
Decomposition by elimination

Algorithm

$$C_r = C_\gamma,$$

- 1 Choose a simple cycle c in C_r ,
- 2 Add c to U_γ ,
- 3 Remove c from C_r : $C_r - c$,
- 4 If C_r is not simple, go to 1.
Add C_r to U_γ .

Example:



$$C_r : a_1 + a_2 + a_3 + a_4 + a_5 + a_6 + a_7 + a_8 + a_9 = 0,$$



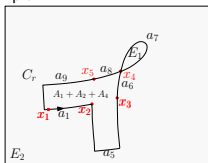
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- 3 Remove c from C_r : $C_r = C_r - c$,
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Example:



$$C_r : a_1 + a_5 + a_6 + a_7 + a_8 + a_9 = 0,$$



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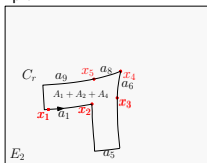
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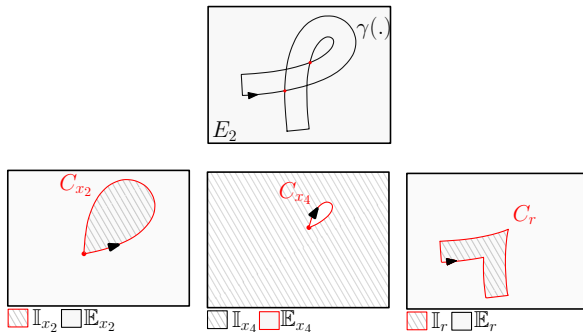


$$C_r : a_1 + a_5 + a_6 + a_7 + a_8 + a_9 = 0,$$

- 1 $c = C_{x_4} : a_7 = 0$
- 2 $U_\gamma = \{C_{x_2}, C_{x_4}\},$
- 3 $C_r : C_r - c = a_1 + a_5 + a_6 + a_8 + a_9 = 0.$
 $U_\gamma = \{C_{x_2}, C_{x_4}, C_r\},$



The winding number of non-simple cycles



$$U_\gamma = \{C_{x_2}, C_{x_4}, C_r\} \text{ and } Z_\gamma = 1$$

$$\eta(\gamma(\cdot), p) = -Z_\gamma + \sum_{u \in U_\gamma} \chi_u(p) = \chi_{I_{x_2}} + \chi_{I_{x_4}} + \chi_{I_r} - 1$$



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Daurade



Courtesy of DGA/GESMA

Data

- DVL,
- IMU,
- Pressure.

Mission

- Classical survey path (law-mowing pattern),
- Roadstead of Brest (France, Brittany),
- 47 minutes.



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Conclusions

Using the topological properties of the robot's exteroceptive sensors contour, we are able to

- determine the area explored during a mission,
- determine the number of times a point in the space was in the robot's range of visibility,



Future Work

- Consider cases where the sensor's contour moves backwards,
- Test the algorithm in real time.



[1] S. G. Krantz.

The index or winding number of a curve about a point.

In *Handbook of Complex Variables*, pages 49–50, Boston, MA, 1999.

